

Some solutions of MHD equations

↳ Comment

1. Eqn of isothermal MHD

$$\rho \left[\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} \right] = \nu \nabla^2 \mathbf{u} - \nabla p + \frac{\mathbf{J} \times \mathbf{B}}{\mu_0}$$

$$\partial_t \rho + \nabla \cdot (\rho \mathbf{u}) = 0$$



$$\partial_t \mathbf{B} + (\mathbf{u} \cdot \nabla) \mathbf{B} = (\mathbf{B} \cdot \nabla) \mathbf{u} - (\nabla \cdot \mathbf{u}) \mathbf{B}$$

$$p = c_s^2 \rho$$

• comments

1. non-linearity
2. Existence of solutions.
3. Hydrodynamic limit, and complexity of solutions, connection with turbulence.

$$\left. \begin{aligned} \partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} &= \nu \nabla^2 \mathbf{u} - \nabla p \\ \nabla \cdot \mathbf{u} &= 0 \end{aligned} \right\}$$

4. Turbulence is ubiquitous.

2. How to solve eqns of MHD.

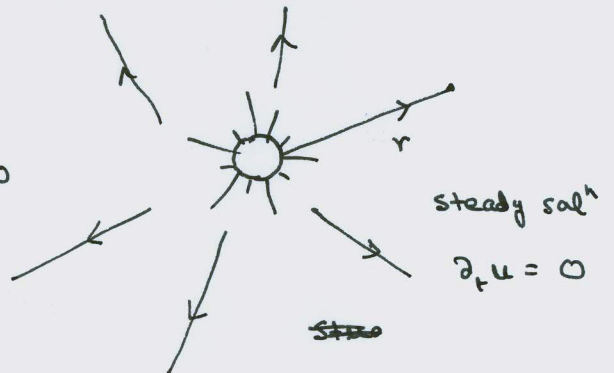
Step 1. Look for symmetry, $\vec{B} = 0$,

$$u_r = u, u_\theta = u_\phi = 0, \partial_\theta = 0, \partial_\phi = 0$$

$$\Rightarrow \rho u \frac{du}{dr} = -\frac{dp}{dr} - \frac{GM\rho}{r^2}$$

and $\frac{1}{r^2} \frac{d}{dr} (r^2 \rho u) = 0$

with $p = c_s^2 \rho \rightarrow$ isothermal

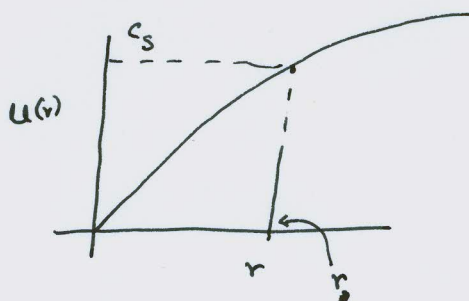


Integrate to obtain: $\frac{1}{2} u^2 + c_s^2 \ln \rho - \frac{GM}{r} = \text{constant} \equiv \mathcal{E} \leftarrow \text{energy}$

$4\pi r^2 \rho u = \text{constant} = \dot{m} \leftarrow \text{mass flux}$

Problem solved! To obtain u , eliminate ρ , to obtain:

$$\frac{1}{2} u^2 - c_s^2 \ln u - 2c_s^2 \ln r - \frac{GM}{r} = \mathcal{E}', \quad \mathcal{E}' = \mathcal{E} - c_s^2 \ln \left(\frac{\dot{m}}{4\pi} \right)$$



$$S = \left(\frac{GM}{2r_s} \right)^{1/2}$$

$$r_s \sim 5R_\odot$$

Parker Wind

3. How to solve eqns of MHD

step 2 stability of the solution.

$$\rho(\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u}) = \nu \nabla^2 \mathbf{u} - \nabla p + \frac{\mathbf{J} \times \mathbf{B}}{\mu_0}$$

\swarrow magnetic pressure
 $-\frac{1}{2} \nabla B^2$
 \searrow $\mathbf{B} \cdot \nabla \mathbf{B}$

$$\partial_t \rho + \nabla \cdot (\rho \mathbf{u}) = 0$$

$$\partial_t \mathbf{B} + (\mathbf{u} \cdot \nabla) \mathbf{B} = (\mathbf{B} \cdot \nabla) \mathbf{u} - (\nabla \cdot \mathbf{u}) \mathbf{B} + \eta \nabla^2 \mathbf{B}$$

$$\mathbf{u} \rightarrow \mathbf{u}_0 + \delta \mathbf{u}; \quad \mathbf{B} \rightarrow \mathbf{B}_0 + \delta \mathbf{b}, \quad \rho \rightarrow \rho_0 + \delta \rho$$

Substitute and expand:

$$\begin{aligned} (\mathbf{u} \cdot \nabla) \mathbf{u} &= (\mathbf{u}_0 + \delta \mathbf{u}) \cdot \nabla (\mathbf{u}_0 + \delta \mathbf{u}) \\ &= (\mathbf{u}_0 \cdot \nabla) \mathbf{u}_0 + (\delta \mathbf{u} \cdot \nabla) \mathbf{u}_0 + (\mathbf{u}_0 \cdot \nabla) \delta \mathbf{u} + (\delta \mathbf{u} \cdot \nabla) \delta \mathbf{u} \end{aligned}$$

Ignore second order terms (infinitesimal perturbation)

to obtain:

$$\left. \begin{aligned} \rho_0 \partial_t \delta \mathbf{u} &= -\rho_0 c_s^2 \nabla \delta \rho - \nabla \left(\frac{\mathbf{B}_0 \cdot \delta \mathbf{b}}{\mu_0} \right) + \frac{1}{\mu_0} (\mathbf{B}_0 \cdot \nabla) \delta \mathbf{b} \\ \partial_t \delta \mathbf{b} &= (\mathbf{B}_0 \cdot \nabla) \delta \mathbf{u} - (\nabla \cdot \delta \mathbf{u}) \mathbf{B}_0 \end{aligned} \right\} \text{Ignore dissipation}$$

$$\partial_t \delta \rho + \rho_0 (\nabla \cdot \delta \mathbf{u}) = 0$$

This is a linear problem; that can be solved by Fourier transform and matrices.

$$\delta \mathbf{u} = \tilde{\mathbf{u}} \exp(-i\omega t + i\vec{k} \cdot \vec{x}), \quad \delta \mathbf{b} = \tilde{\mathbf{b}} \exp(-i\omega t + i\vec{k} \cdot \vec{x})$$

$$\delta \rho = \tilde{\rho} \exp(-i\omega t + i\vec{k} \cdot \vec{x})$$

Typically takes the form:

Also

$$\mathcal{M}(\psi) = 0$$

A solution exists only when $\det \mathcal{M} = 0$

$$\begin{pmatrix} -i\omega & * & * & * & * \\ & * & * & * & * \\ * & & & & \\ * & & & & \\ * & & & & -i\omega \end{pmatrix} \begin{pmatrix} \tilde{u}_x \\ \tilde{u}_y \\ \tilde{u}_z \\ \tilde{\rho} \\ \tilde{b}_x \\ \tilde{b}_y \\ \tilde{b}_z \end{pmatrix} = 0$$

det M = 0 \Rightarrow (a 7th order polynomial in ω) = 0 (3)

consider a simple example : $B_0 = \hat{z} B_0$, $u_0 = 0$, $\rho_0 = \text{constant}$

and assume we live in 1-d space, i.e. $\vec{k} = (0, 0, k_z)$

Then or $\partial_z = \text{nonzero}$, $\partial_x = 0$, $\partial_y = 0$.

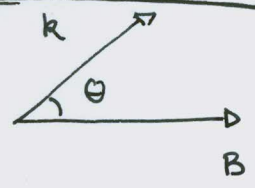
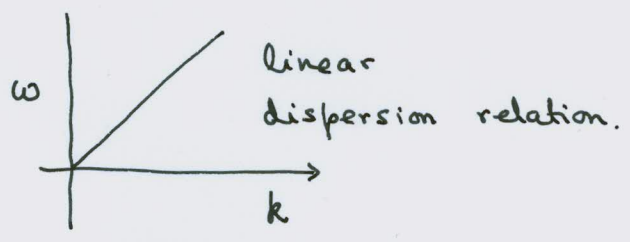
The problem simplifies to a simpler eqns:

$\omega = 0$, $\omega^2 - c_s^2 k^2 = 0$ $\omega^4 - 2v_A^2 k^2 \omega^2 + v_A^4 k^4 = 0$ (7 roots in total)

with $v_A = \frac{B_0}{\sqrt{\rho_0 \mu_0}}$ sound waves

$(\omega^2 - v_A^2 k^2)^2 = 0$ Alfvén wave.

Transverse wave. magnetic field behaves like a string



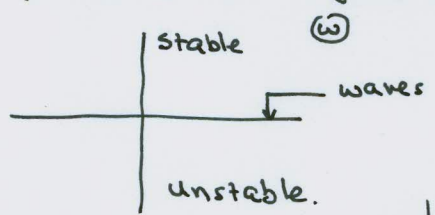
In a more complex 3d case one obtains

$\omega = 0$, $\omega^4 - \omega^2 k^2 (v_A^2 + c_s^2) + k^4 v_A^2 c_s^2 \cos^2 \theta = 0$, $\omega^2 + k^2 v_A^2 = 0$

fast and slow magnetosonic wave (two roots each, 4 in total) Alfvén wave (two roots)

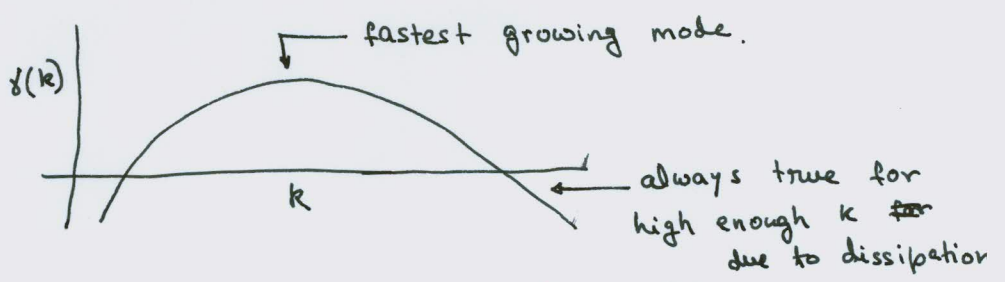
Comments

1. ω could in general be: real : waves



+ve imaginary : $i\gamma(k) \rightarrow$ decaying solⁿ
 -ve imaginary : $-i\gamma(k) \rightarrow$ growing solⁿ

In general for unstable case:



Mechanism of pattern formation in complex systems.

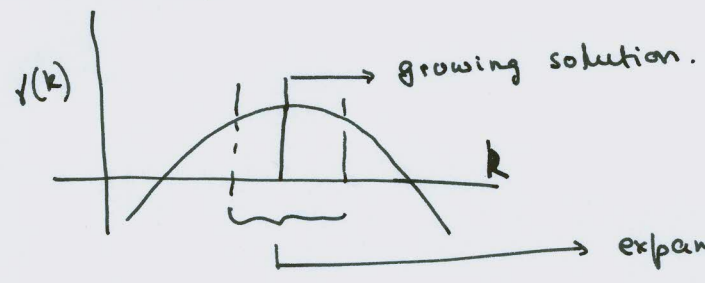
An important example is the magnetorotational instability (MRI)

2. For complex geometries, even the linear equations cannot be solved analytically. One ~~may~~ must construct, numerically, the matrix M and then ~~is~~ numerically diagonalize it. This is a field of active research. ~~the~~ ~~as~~ we can make significant progress if we try to look for only the fastest growing mode.

3. The linear theory is not very useful. Linearly stable flows can be actually unstable. A typical example is the pipe flow, which is linearly stable but of course turbulent in practice.

4. Saturation cannot be described by linear theory. There may be ~~second~~ secondary instabilities. It is possible to study beyond linear stability by weakly nonlinear perturbative approach.

$\partial_t \psi = \gamma \psi \leftarrow$ linear growth. \leftarrow



Note the need for seed fields

~~The saturation can be determined~~

order $\partial_t \psi = \gamma \psi - \mu \psi^2$
 \uparrow
 saturation.

5. Pay attention to dissipation. It cannot be arbitrarily set to zero. $\nu = 0$, and $\nu \rightarrow 0$ limit can be very different. $\nu \rightarrow 0$ is the limit of reconnection.

4. How to solve eqn of MHD

step 3 Crave up and use a computer.

There exists a kaleidoscope of codes; each working in a limited domain, all limited by our computing power. For example, the simulation of the sun corresponds to a sun, not filled with plasma, but with honey. see the talk by Prateek sharma.

To summarize: our knowledge of the solutions of MHD eqn is very limited. The main research question is how can we describe the natural phenomenon as solutions of the MHD equations.

References

- Astrophysical fluids and plasmas - by Arnab Rai Chaudhuri. Possibly the best introductory book in this subject.
- Best be sure to read Parker's original paper on the solar wind problem.
- About MRI, read the paper by Balbus and Hawley in Rev. Mod. Phys.
- As an example of application of weakly nonlinear approach to study saturation of a by MHD instability see arXiv: 1011.1251